

Introduction to barycentric geometry with applications.

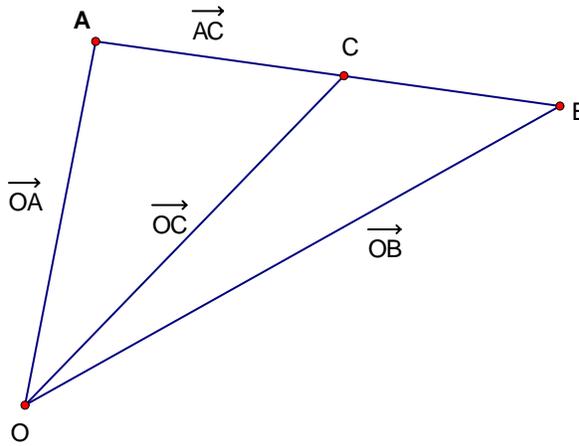
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Some preliminary facts.

First recall that any two non collinear vectors \vec{OA}, \vec{OB} create a basis on the plane with origin O , that is for any vector \vec{OC} there are unique

$p, q \in \mathbb{R}$ such that $\vec{OC} = p\vec{OA} + q\vec{OB}$ and we saying that pair (p, q) is coordinates of \vec{OC} in the basis (\vec{OA}, \vec{OB}) and \vec{OC} is linear combination of \vec{OA} and \vec{OB} with

coefficients p and q . Also note that point C belong to the segment AB iff \vec{OC} is linear combination of vectors \vec{OA}, \vec{OB} with non negative coefficients p and such that $p + q = 1$. (in that case we saying that \vec{OC} is convex combination of vectors \vec{OA}, \vec{OB} or that segment AB is convex combination of his ends).



Indeed let C belong to the segment AB . If $C \in \{A, B\}$ then $\vec{AC} = k\vec{AB}$, where $k \in \{0, 1\}$. If $C \notin \{A, B\}$ then \vec{AC} is collinear with \vec{AB} and directed as \vec{AB} , that is $\vec{AC} = k\vec{AB}$ for some positive k . Hence, $\|\vec{AC}\| =$

$$\|k\vec{AB}\| = k\|\vec{AB}\| \iff k = \frac{\|\vec{AC}\|}{\|\vec{AB}\|} < 1.$$

Thus, if C belong to the segment AB then $\vec{AC} = k\vec{AB}$ with $k \in [0, 1]$ and since $\vec{AC} = \vec{AO} + \vec{OC} = \vec{OC} - \vec{OA}$, $\vec{AB} = \vec{AO} + \vec{OB} = \vec{OB} - \vec{OA}$ then $\vec{AC} = k\vec{AB} \iff \vec{OC} - \vec{OA} = k(\vec{OB} - \vec{OA}) \iff \vec{OC} = k\vec{OB} - k\vec{OA} + \vec{OA} \iff$

$$\vec{OC} = (1 - k)\vec{OA} + k\vec{OB} \iff \vec{OC} = p\vec{OA} + q\vec{OB}, \text{ where } p := 1 - k, q := k, \text{ that is } p, q \geq 0 \text{ and } p + q = 1.$$

Opposite, let $\vec{OC} = p\vec{OA} + q\vec{OB}$, where $p + q = 1$ and $p, q \geq 0$. Then, by reversing transformation above we obtain $\vec{AC} = q\vec{AB}$, $q \in [0, 1]$. and since $\vec{CB} = \vec{CA} + \vec{AB} = \vec{AB} - \vec{AC} = \vec{AB} - q\vec{AB} = (1 - q)\vec{AB}$ we obtain

$\|\overrightarrow{AC}\| = q\|\overrightarrow{AB}\|, \|\overrightarrow{CB}\| = (1-q)\|\overrightarrow{AB}\|$. Therefore, $\|\overrightarrow{AB}\| = \|\overrightarrow{AC}\| + \|\overrightarrow{CB}\| \iff C$ belong to the segment AB .

(Another variant:

Let $\mathbf{a} := \overrightarrow{OA}, \mathbf{b} := \overrightarrow{OB}$ and $\mathbf{c} := \overrightarrow{OC}$. Note that $C \in AB$ iff $\mathbf{c} - \mathbf{a}$ is collinear to $\mathbf{b} - \mathbf{a}$, that is $\mathbf{c} - \mathbf{a} = k(\mathbf{b} - \mathbf{a})$ for some real k and $|AC| + |CB| = |AB|$, that is $\|\mathbf{c} - \mathbf{a}\| + \|\mathbf{b} - \mathbf{c}\| = \|\mathbf{b} - \mathbf{a}\|$. Thus,

$$C \in AB \iff \begin{cases} \mathbf{c} - \mathbf{a} = k(\mathbf{b} - \mathbf{a}) \\ \|\mathbf{c} - \mathbf{a}\| + \|\mathbf{b} - \mathbf{c}\| = \|\mathbf{b} - \mathbf{a}\| \end{cases}$$

Since

$$\mathbf{b} - \mathbf{c} = \mathbf{b} - \mathbf{a} - (\mathbf{c} - \mathbf{a}) = \mathbf{b} - \mathbf{a} - k(\mathbf{b} - \mathbf{a}) = (1-k)(\mathbf{b} - \mathbf{a})$$

then

$$\begin{aligned} \|\mathbf{c} - \mathbf{a}\| + \|\mathbf{b} - \mathbf{c}\| = \|\mathbf{b} - \mathbf{a}\| &\iff \|k(\mathbf{b} - \mathbf{a})\| + \|(1-k)(\mathbf{b} - \mathbf{a})\| = \|\mathbf{b} - \mathbf{a}\| \iff \\ |k|\|(\mathbf{b} - \mathbf{a})\| + |(1-k)|\|(\mathbf{b} - \mathbf{a})\| = \|\mathbf{b} - \mathbf{a}\| &\iff |k| + |1-k| = 1 \iff 0 \leq k \leq 1. \end{aligned}$$

Hence, $C \in AB \iff \mathbf{c} - \mathbf{a} = k(\mathbf{b} - \mathbf{a}) \iff \mathbf{c} = \mathbf{a}(1-k) + k\mathbf{b}$, where $k \in [0, 1]$.

Barycentric coordinates.

Let A, B, C be vertices of non-degenerate triangle. Then, since \overrightarrow{AB} and \overrightarrow{AC} non-collinear, then for each point P on plain we have unique representation $\overrightarrow{AP} = k\overrightarrow{AB} + l\overrightarrow{AC}$, where $k, l \in \mathbb{R}$. Let O be a any point fixed on the plain. Then since $\overrightarrow{AP} = \overrightarrow{AO} + \overrightarrow{OP}, \overrightarrow{AB} = \overrightarrow{AO} + \overrightarrow{OB}, \overrightarrow{AC} = \overrightarrow{AO} + \overrightarrow{OC}$ we obtain $\overrightarrow{AO} + \overrightarrow{OP} = k(\overrightarrow{AO} + \overrightarrow{OB}) + l(\overrightarrow{AO} + \overrightarrow{OC}) \iff \overrightarrow{OP} = (1-k-l)\overrightarrow{OA} + k\overrightarrow{OB} + l\overrightarrow{OC}$. Denote $p_a := 1-k-l, p_b := k, p_c := l$, then $p_a + p_b + p_c = 1$ and $\overrightarrow{OP} = p_a\overrightarrow{OA} + p_b\overrightarrow{OB} + p_c\overrightarrow{OC}$.

Suppose we have another such representation $\overrightarrow{OP} = q_a\overrightarrow{OA} + q_b\overrightarrow{OB} + q_c\overrightarrow{OC}$ with $q_a + q_b + q_c = 1$, then $\overrightarrow{AP} = p_b\overrightarrow{AB} + p_c\overrightarrow{AC} = q_b\overrightarrow{AB} + q_c\overrightarrow{AC} \implies p_b = q_b, p_c = q_c \implies p_a = q_a$.

Since for each point P we have unique ordered triple of real numbers (p_a, p_b, p_c) which satisfy to condition $p_a + p_b + p_c = 1$ and since any such ordered triple determine some point on plain, then will call such triples barycentric coordinates of point P with respect to triangle ΔABC , because in reality barycentric coordinates independent from origin O . Indeed let O_1 another origin, then

$$\begin{aligned} \overrightarrow{O_1P} = \overrightarrow{O_1O} + \overrightarrow{OP} &= (p_a + p_b + p_c)\overrightarrow{O_1O} + p_a\overrightarrow{OA} + p_b\overrightarrow{OB} + p_c\overrightarrow{OC} = \\ p_a(\overrightarrow{O_1O} + \overrightarrow{OA}) + p_b(\overrightarrow{O_1O} + \overrightarrow{OB}) + p_c(\overrightarrow{O_1O} + \overrightarrow{OC}) &= p_a\overrightarrow{O_1A} + p_b\overrightarrow{O_1B} + p_c\overrightarrow{O_1C} \end{aligned}$$

If $p_a, p_b, p_c > 0$ then P is interior point of triangle and in that case we have clear geometric interpretation of numbers p_a, p_b, p_c . Really, since $\vec{OP} = p_a \vec{OA} + (p_b + p_c) \left(\frac{p_b}{p_b + p_c} \vec{OB} + \frac{p_c}{p_b + p_c} \vec{OC} \right)$ then linear combination $\frac{p_b}{p_b + p_c} \vec{OB} + \frac{p_c}{p_b + p_c} \vec{OC}$ determine some point A_1 on the segment BC , such that

$$\vec{OA_1} = \frac{p_b}{p_b + p_c} \vec{OB} + \frac{p_c}{p_b + p_c} \vec{OC} \text{ and } \vec{OP} = p_a \vec{OA} + (p_a + p_b) \vec{OA_1}.$$

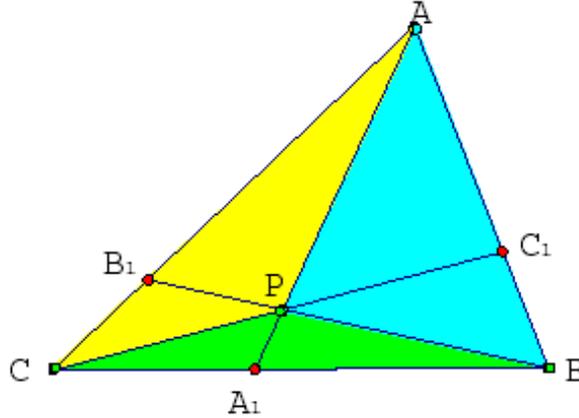
In particular, $\vec{AP} = (p_b + p_c) \vec{OA_1}$. So, P belong to the segment AA_1 and divide it in the ratio $AP \div PA_1 = (p_b + p_c) \div p_a$.

By the same way we obtain points B_1, C_1 on CA, AB , respectively, and

$$BP \div PB_1 = (p_c + p_a) \div p_b, CP \div PC_1 = (p_a + p_b) \div p_c.$$

Denote $F_a := [PBC]$, $F_b := [PCA]$, $F_c := [PAB]$, $F := [ABC]$ then $p_c \div p_a = AB_1 \div CB_1 = F_c \div F_a$, $p_a \div p_b = BC_1 \div AC_1 = F_a \div F_b$, $p_b \div p_c =$

$BC_1 \div AC_1 = F_b \div F_c$. So, $p_a \div p_b \div p_c = F_a \div F_b \div F_c$
and $p_a = \frac{F_a}{F}$, $p_b = \frac{F_b}{F}$, $p_c = \frac{F_c}{F}$.



Application 1. Barycentric coordinates of some triangle centres.

Problem 1.

Find barycentric coordinates of the following Triangle centres:

- a) Centroid G (the point of concurrency of the medians);
- b) Incenter I (the point of concurrency of the interior angle bisectors);
- c) Orthocenter H of an acute triangle (the point of concurrency of the altitudes);
- d) Circumcenter O .

Solution.

a) Since for $P = G$ we have $F_a = F_b = F_c$ then $(p_a, p_b, p_c) = (1/3, 1/3, 1/3)$ is barycentric coordinates of centroid G .

b) Since for $P = I$ we have $\frac{F_c}{F_b} = \frac{BA_1}{A_1C} = \frac{c}{b}, \frac{F_a}{F_b} = \frac{BC_1}{C_1A} = \frac{a}{b}$ then

$F_a \div F_b \div F_c = a \div b \div c$ and, therefore, $(p_a, p_b, p_c) = \frac{1}{a+b+c} (a, b, c)$

is barycentric coordinates of incenter I .

c) For $P = H$ we have

$$BA_1 = c \cos B, A_1C = b \cos C, BC_1 = a \cos B, C_1A = b \cos A.$$

Hence, $\frac{F_c}{F_b} = \frac{BA_1}{A_1C} = \frac{c \cos B}{b \cos C} = \frac{2R \sin C \cos B}{2R \sin B \cos C} = \frac{\tan C}{\tan B}, \frac{F_a}{F_b} = \frac{BC_1}{C_1A} = \frac{a \cos B}{b \cos A} = \frac{\tan A}{\tan B}$

$$\iff F_a \div F_b \div F_c = \tan A \div \tan B \div \tan C \text{ and, since } \frac{1}{\tan A + \tan B + \tan C} (\tan A, \tan B, \tan C) = \frac{1}{\tan A \tan B \tan C} (\tan A, \tan B, \tan C) = (\cot B \cot C, \cot C \cot A, \cot A \cot B), \text{ then}$$

$$(p_a, p_b, p_c) = (\cot B \cot C, \cot C \cot A, \cot A \cot B)$$

is barycentric coordinates of orthocenter H .

d) For $P = O$ since $\angle BOC = 2A, \angle COA = 2B, \angle AOB = 2C$ we have $F_a = \frac{R^2 \sin 2A}{2}, F_b = \frac{R^2 \sin 2B}{2}, F_c = \frac{R^2 \sin 2C}{2}$ and, therefore*, $(p_a, p_b, p_c) =$

$$\frac{1}{\sin 2A + \sin 2B + \sin 2C} (\sin 2A, \sin 2B, \sin 2C) = \frac{1}{4 \sin A \sin B \sin C} (\sin 2A, \sin 2B, \sin 2C) = \left(\frac{\cos A}{\sin B \sin C}, \frac{\cos B}{\sin C \sin A}, \frac{\cos C}{\sin A \sin B} \right)$$

is barycentric coordinates of circumcenter O .

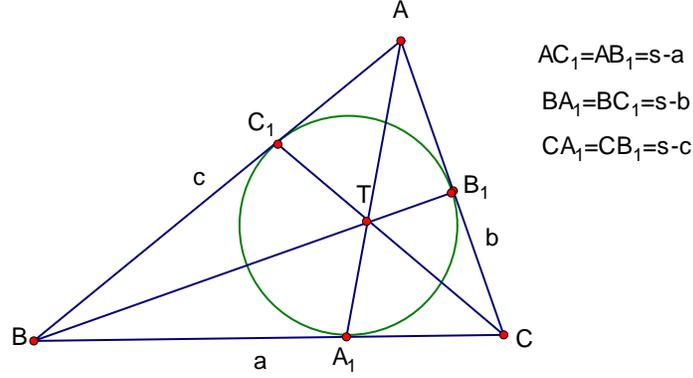
* Note that $\sin 2A + \sin 2B + \sin 2C = 4 \sin A \sin B \sin C$.

Problem 2.

a) Let A_1, B_1, C_1 be, respectively, points of tangency of incircle to sides BC, CA, AB of a triangle ABC . Prove that cevians AA_1, BB_1, CC_1 are intersect at one point and find barycentric coordinates of this point.

b) The same questions if A_1, B_1, C_1 be, respectively, points where excircles tangent sides BC, CA, AB .

Solution.

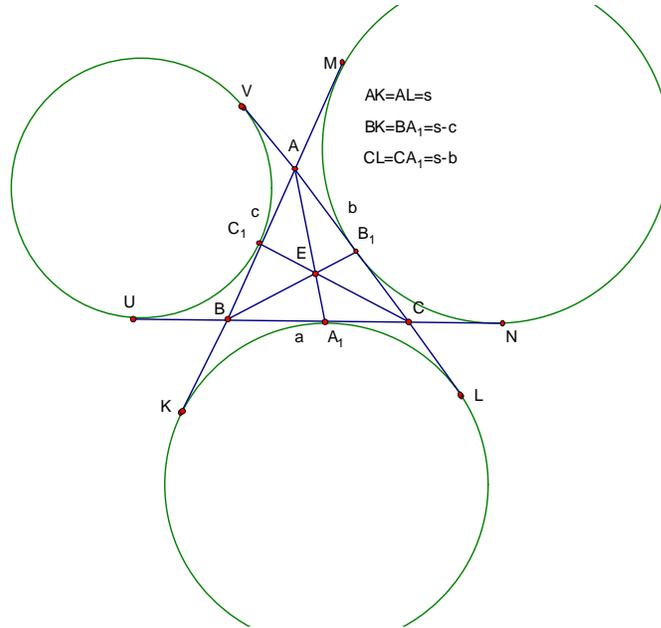


a)

Since $AC_1 = B_1A = s - a$, $C_1B = BA_1 = s - b$, $A_1C = CB_1 = s - c$ then $\frac{BA_1}{A_1C} \cdot \frac{CB_1}{B_1A} \cdot \frac{AC_1}{C_1B} = \frac{s-b}{s-c} \cdot \frac{s-c}{s-a} \cdot \frac{s-a}{s-b} = 1$ and, therefore, by converse of Ceva's Theorem cevians AA_1, BB_1, CC_1 are concurrent. Let T be point of intersection of these cevians. For $P = T$ we have $\frac{F_c}{F_b} = \frac{BA_1}{A_1C} = \frac{s-b}{s-c} = \frac{1/(s-c)}{1/(s-b)} = \frac{(s-b)(s-a)}{(s-c)(s-a)}$, $\frac{F_a}{F_b} = \frac{C_1B}{AC_1} = \frac{s-b}{s-a} = \frac{1/(s-a)}{1/(s-b)} = \frac{(s-b)(s-c)}{(s-c)(s-a)}$.

Hence, $F_a \div F_b \div F_c = (s-b)(s-c) \div (s-c)(s-a) \div (s-a)(s-b) = \frac{1}{s-a} \div \frac{1}{s-b} \div \frac{1}{s-c}$. Let r_a, r_b, r_c be exradii of $\triangle ABC$. Since $r_a(s-a) = r_b(s-b) = r_c(s-c) = F$ and $r_a + r_b + r_c = 4R + r$ then $F_a \div F_b \div F_c = r_a \div r_b \div r_c$ and, therefore,

$$(p_a, p_b, p_c) = \frac{1}{4R + r} (r_a, r_b, r_c)$$

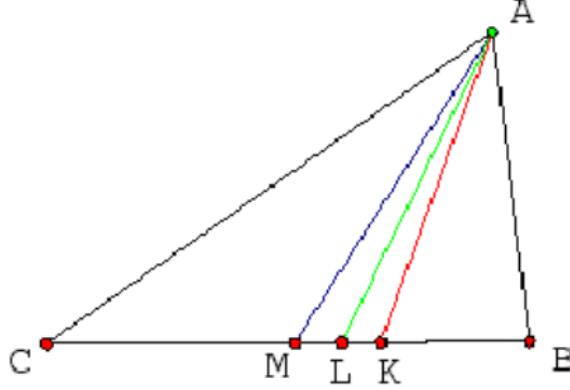


b)

Let $x := BA_1, y := CA_1$. Then $x + y = a$, $AK = AL \iff c + x = b + y$ and, therefore, $2x = x + y + x - y = a + b - c \iff x = s - c, y = s - b$ and $AK = AL = s$. Thus $BA_1 = BK = s - c, A_1C = CL = s - b$. Similarly, $B_1A = s - c, AC_1 = s - b$ and $BC_1 = CB_1 = s - a$. Then $\frac{BA_1}{A_1C} \cdot \frac{CB_1}{B_1A} \cdot \frac{AC_1}{C_1B} = \frac{s-c}{s-b} \cdot \frac{s-a}{s-c} \cdot \frac{s-b}{s-a} = 1$ and, therefore, by converse of Ceva's Theorem cevians AA_1, BB_1, CC_1 are concurrent. Let E be point of intersection of these cevians. For $P = E$ we have $\frac{F_c}{F_b} = \frac{BA_1}{A_1C} = \frac{s-c}{s-b}, \frac{F_a}{F_b} = \frac{C_1B}{AC_1} = \frac{s-a}{s-b}$. Hence, $F_a \div F_b \div F_c = (s-a) \div (s-b) \div (s-c)$ and, therefore, $(p_a, p_b, p_c) = \frac{1}{s}(s-a, s-b, s-c)$.

Problem 3.

Find barycentric coordinates of **Lemoine point** (point of intersection of symmedians). (A -symmedian of triangle ABC is the reflection of the A -median in the A -internal angle bisector).



pic.1

Let AM, AL, AK be respectively median, angle-bisector and symmedian of $\triangle ABC$ and let $a := BC, b := CA, c := AB, m_a := AM, w_a := AL, k_a := AK, p := ML, q := KL$. Suppose also, that $b \geq c$. Since AL is symmedian in $\triangle ABC$ then AL is angle-bisector in triangle MAK and that imply $\frac{m_a}{p} = \frac{k_a}{q}$, i.e. there is $t > 0$ such that $k_a = tm_a$ and $q = tp$. Applying Stewart's Formula to chevian AL in triangle MAK we obtain: $w_a^2 = m_a^2 \cdot \frac{q}{p+q} + k_a^2 \cdot \frac{p}{p+q} - (p+q)^2 \cdot \frac{pq}{(p+q)^2} = m_a^2 \cdot \frac{q}{p+q} + k_a^2 \cdot \frac{p}{p+q} - pq = \frac{tm_a^2}{1+t} + \frac{k_a^2}{1+t} - tp^2$, because $\frac{p}{p+q} = \frac{1}{1+t}, \frac{q}{p+q} = \frac{t}{1+t}$. Since AL angle-bisector in $\triangle ABC$ then $CL = \frac{ab}{b+c}$ and $p = \frac{ab}{b+c} - \frac{a}{2} = \frac{a(b-c)}{2(b+c)}$. By substitution $w_a^2 = \frac{bc((b+c)^2 - a^2)}{(b+c)^2}, m_a^2 = \frac{2(b^2+c^2) - a^2}{4}, p = \frac{a(b-c)}{2(b+c)}$ and $k_a = tm_a$ in $w_a^2 = \frac{tm_a^2}{1+t} + \frac{k_a^2}{1+t} - tp^2$ we obtain:

$$\begin{aligned} \frac{tm_a^2}{1+t} + \frac{k_a^2}{1+t} - tp^2 &= \frac{tm_a^2}{1+t} + \frac{t^2m_a^2}{1+t} - tp^2 = t(m_a^2 - p^2) = \\ t \left(\frac{b^2+c^2}{2} - \frac{a^2}{4} \left(1 + \frac{(b-c)^2}{(b+c)^2} \right) \right) &= t \left(\frac{b^2+c^2}{2} - \frac{a^2(b^2+c^2)}{2(b+c)^2} \right) = \\ \frac{t((b+c)^2 - a^2)(b^2+c^2)}{2(b+c)^2} &= \frac{bc((b+c)^2 - a^2)}{(b+c)^2}. \end{aligned}$$

$$\text{Hence, } t = \frac{2bc}{b^2 + c^2}, k_a = \frac{2bcm_a}{b^2 + c^2} = \frac{bc\sqrt{2(b^2 + c^2) - a^2}}{b^2 + c^2}, p+q = \frac{a(b-c)}{2(b+c)}(1+t) =$$

$$\frac{a(b-c)}{2(b+c)} \cdot \frac{(b+c)^2}{b^2 + c^2} = \frac{a(b^2 - c^2)}{2(b^2 + c^2)} \text{ and } \frac{CK}{KB} = \frac{\frac{a}{2} + p + q}{\frac{a}{2} - (p+q)} = \frac{b^2}{c^2}.$$

So, if L is Lemoine's Point (point of intersection of symmedians of $\triangle ABC$) then for barycentric coordinates (L_a, L_b, L_c) of L holds $L_a \div L_b \div L_c = a^2 \div b^2 \div c^2$.

Distances Formulas.

1. Stewart's Formula for length of chevian.

Let $\vec{OP} = p_a\vec{OA} + p_b\vec{OB}$, $p_a + p_b = 1$, then $OP^2 = \vec{OP} \cdot \vec{OP} =$

$$\left(p_a\vec{OA} + p_b\vec{OB}\right) \cdot \left(p_a\vec{OA} + p_b\vec{OB}\right) = p_a^2OA^2 + p_b^2OB^2 + 2p_ap_b\left(\vec{OA} \cdot \vec{OB}\right) =$$

$$p_a(1 - p_b)OA^2 + p_b(1 - p_a)OB^2 + 2p_ap_b\left(\vec{OA} \cdot \vec{OB}\right) =$$

$$p_aOA^2 + p_bOB^2 - p_ap_bOA^2 - p_ap_bOB^2 + 2p_ap_b\left(\vec{OA} \cdot \vec{OB}\right) = p_aOA^2 + p_bOB^2 - p_ap_bAB^2.$$

So, $OP^2 = p_aOA^2 + p_bOB^2 - p_ap_bAB^2$. (Stewart's Formula).

2. Lagrange's Formula.

Let (p_a, p_b, p_c) be baycentric coordinates of the point P , i.e. $p_a + p_b + p_c = 1$ and $\vec{OP} = p_a\vec{OA} + p_b\vec{OB} + p_c\vec{OC}$, then $OP^2 = \vec{OP} \cdot \vec{OP} = \left(p_a\vec{OA} + p_b\vec{OB} + p_c\vec{OC}\right) \cdot \vec{OP} = p_a\vec{OA} \cdot \vec{OP} + p_b\vec{OB} \cdot \vec{OP} + p_c\vec{OC} \cdot \vec{OP} =$

$$p_a\vec{OA} \cdot \left(\vec{OA} + \vec{AP}\right) + p_b\vec{OB} \cdot \left(\vec{OB} + \vec{BP}\right) + p_c\vec{OC} \cdot \left(\vec{OC} + \vec{CP}\right) =$$

$$\sum_{cyc} \left(p_aOA^2 + p_a\vec{OA} \cdot \vec{AP}\right) = \sum_{cyc} p_aOA^2 + \sum_{cyc} p_a\left(\vec{OP} + \vec{PA}\right) \cdot \vec{AP} =$$

$$\sum_{cyc} p_aOA^2 + \sum_{cyc} p_a\left(\vec{OP} - \vec{AP}\right) \cdot \vec{AP} = \sum_{cyc} p_a\left(OA^2 - PA^2\right) + \sum_{cyc} p_a\vec{OP} \cdot \vec{AP} =$$

$$\sum_{cyc} p_a\left(OA^2 - PA^2\right) + \vec{OP} \cdot \sum_{cyc} p_a\vec{AP} = \sum_{cyc} p_a\left(OA^2 - PA^2\right)$$

So, $OP^2 = \sum_{cyc} p_a\left(OA^2 - PA^2\right)$ (**Lagrange's formula**).

Remark.

As a corollary from Lagrange's formula we obtain two identities which can be useful.

Let P and Q be two points on plane with barycentric coordinates (p_a, p_b, p_c) and $Q(q_a, q_b, q_c)$, respectively. Since $QP^2 = \sum_{cyc} p_a (QA^2 - PA^2)$ and $PQ^2 = \sum_{cyc} q_a (PA^2 - QA^2)$ we obtain

$$PQ^2 = \frac{1}{2} \sum_{cyc} (p_a - q_a) (QA^2 - PA^2) \quad \text{and} \quad \sum_{cyc} (p_a + q_a) (PA^2 - QA^2) = 0.$$

3. Leibnitz Formula

Let A_1, B_1, C_1 be points intersection of lines PA, PB, PC with BC, CA, AB respectively. Applying Stewart Formula to $O = A_1, P$ and B, C and taking in account that $BA_1 \div CA_1 = p_c \div p_b$ we obtain

$$A_1P^2 = \frac{p_b}{p_b + p_c} PB^2 + \frac{p_c}{p_b + p_c} PC^2 - \frac{p_b}{p_b + p_c} \cdot \frac{p_c}{p_b + p_c} a^2$$

and, and since $\overrightarrow{A_1P} = -\frac{p_a}{p_b + p_c} \overrightarrow{AP}$ then $A_1P^2 = \frac{p_a^2}{(p_b + p_c)^2} AP^2$.

Therefore, $\frac{p_a^2}{(p_b + p_c)^2} AP^2 = \frac{p_b}{p_b + p_c} PB^2 + \frac{p_c}{p_b + p_c} PC^2 - \frac{p_b}{p_b + p_c} \cdot \frac{p_c}{p_b + p_c} a^2 \iff$
 $p_a^2 AP^2 = p_b (p_b + p_c) PB^2 + p_c (p_b + p_c) PC^2 - p_b p_c a^2$. Hence, $\sum_{cyc} p_a^2 AP^2 = \sum_{cyc} p_b (p_b + p_c) PB^2 +$
 $\sum_{cyc} p_c (p_b + p_c) PC^2 - \sum_{cyc} p_b p_c a^2 \iff$

$$\sum_{cyc} p_b p_c a^2 = \sum_{cyc} (p_b^2 + p_b p_c) PB^2 + \sum_{cyc} (p_b p_c + p_c^2) PC^2 - \sum_{cyc} p_a^2 AP^2 =$$

$$\sum_{cyc} p_b^2 PB^2 + \sum_{cyc} p_b p_c PB^2 + \sum_{cyc} p_b p_c PC^2 + \sum_{cyc} p_c^2 PC^2 - \sum_{cyc} p_a^2 AP^2 =$$

$$\sum_{cyc} p_b p_c PB^2 + \sum_{cyc} p_b p_c PC^2 + \sum_{cyc} p_c^2 PC^2 = \sum_{cyc} p_b p_c PB^2 + \sum_{cyc} p_c p_a PA^2 + \sum_{cyc} p_c^2 PC^2 =$$

$$\sum_{cyc} p_c (p_b PB^2 + p_a PA^2 + p_c PC^2) = (p_b PB^2 + p_a PA^2 + p_c PC^2) \sum_{cyc} p_c = \sum_{cyc} p_a PA^2$$

Thus, $\sum_{cyc} p_a PA^2 = \sum_{cyc} p_b p_c a^2$ and, therefore, $OP^2 = \sum_{cyc} p_a (OA^2 - PA^2) \iff$

$$OP^2 = \sum_{cyc} p_a OA^2 - \sum_{cyc} p_b p_c a^2 \quad \text{(Leibnitz Formula).}$$

Application of distance formulas.

1. Distance between circumcenter O and centroid G .

Let O be circumcenter, R –circumradius and $P = G \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3} \right)$, then $OG^2 =$

$$\sum_{cyclic} \frac{1}{3} \cdot (R^2 - GA^2) = R^2 - \frac{1}{3} \sum_{cyclic} GA^2.$$

Since $GA^2 = \frac{4}{9} \left(\frac{2(b^2 + c^2) - a^2}{4} \right) = \frac{2(b^2 + c^2) - a^2}{9}$ then $\sum_{cyclic} GA^2 = \frac{a^2 + b^2 + c^2}{3}$ and $OG^2 = R^2 - \frac{a^2 + b^2 + c^2}{9}$.

This imply $R^2 - \frac{a^2 + b^2 + c^2}{9} \geq 0 \iff a^2 + b^2 + c^2 \leq 9R^2$.

**2. Distance between circumcenter O and incenter I .
(Euler’s formula and Euler’s inequality).**

Let O be circumcenter. Since $I \left(\frac{a}{a+b+c}, \frac{b}{a+b+c}, \frac{c}{a+b+c} \right)$, then $(a+b+c)OI^2 = \sum_{cyc} a(OA^2 - IA^2) = \sum_{cyc} a(R^2 - IA^2) = (a+b+c)R^2 - \sum_{cyc} aIA^2$.

Since $aIA^2 = \frac{aw_a^2(b+c)^2}{(a+b+c)^2} = \frac{abc(a+b+c)(b+c-a)(b+c)^2}{(a+b+c)^2(b+c)^2} = \frac{abc(b+c-a)}{a+b+c}$ then

$$\sum_{cyclic} aIA^2 = abc \text{ and } OI^2 = R^2 - \frac{abc}{a+b+c} = R^2 - \frac{4Rrs}{2s} = R^2 - 2Rr.$$

Hence, $OI = \sqrt{R^2 - 2Rr}$ and $R^2 - 2Rr \geq 0 \iff R \geq 2r$.

Remark.

Consider now general situation, when O be circumcenter, R –circumradius of circumcircle of $\triangle ABC$ and (p_a, p_b, p_c) is barycentric coordinates of some point P . Then applying general Leibnitz Formula for such origin O we obtain:

$$OP^2 = \sum_{cyc} p_a OA^2 - \sum_{cyc} p_b p_c a^2 = \sum_{cyc} p_a R^2 - \sum_{cyc} p_b p_c a^2 = R^2 - \sum_{cyc} p_b p_c a^2.$$

Thus $\sum_{cyc} p_b p_c a^2 \leq R^2$ and $OP = \sqrt{R^2 - \sum_{cyc} p_b p_c a^2}$.

Using the formula obtained for the OP , we consider several more cases of calculating the distances between circumcenter O and another triangle centers..

But for beginning we will apply this formula for considered above two cases.

If $P = G \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3} \right)$ then $\sum_{cyc} p_b p_c a^2 = \frac{1}{9} \sum_{cyc} a^2$ and, therefore,

$$OG = \sqrt{R^2 - \frac{a^2 + b^2 + c^2}{9}}$$

;

If $P = I \left(\frac{a}{2s}, \frac{b}{2s}, \frac{c}{2s} \right)$ then $\sum_{cyc} p_b p_c a^2 = \frac{1}{4s^2} \sum_{cyc} bca^2 = \frac{abc(a+b+c)}{4s^2} = \frac{4Rrs \cdot 2s}{4s^2} = 2Rr$ and, therefore,

$$OI = \sqrt{R^2 - 2Rr}$$

3. Distance between circumcenter O and orthocenter H .

Since $H(\cot B \cot C, \cot C \cot A, \cot A \cot B)$ then $\sum_{cyc} p_b p_c a^2 = \sum_{cyc} \cot C \cot A \cdot \cot A \cot B \cdot a^2 = \cot A \cot B \cot C \sum_{cyc} a^2 \cot A$. Noting that $\sum_{cyc} \cot A \cdot a^2 = 4R^2 \sum_{cyc} \cot A \cdot \sin^2 A = 2R^2 \sum_{cyc} \sin 2A = 8R^2 \sin A \sin B \sin C$ and $\cos A \cos B \cos C = \frac{s^2 - (2R+r)^2}{4R^2}$ we obtain $\sum_{cyc} p_b p_c a^2 = \cot A \cot B \cot C \sum_{cyc} a^2 \cot A = \cot A \cot B \cot C \cdot 8R^2 \sin A \sin B \sin C = 8R^2 \cos A \cos B \cos C = 8R^2 \cdot \frac{s^2 - (2R+r)^2}{4R^2} = 2(s^2 - (2R+r)^2)$ and, therefore,

$$OH = \sqrt{R^2 - 2(s^2 - (2R+r)^2)} = \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2}.$$

And by the way we obtain inequality $s^2 \leq \frac{9R^2 + 8Rr + 2r^2}{2}$.

Remark.

This inequality also immediately follows from Gerretsen's Inequality $s^2 \leq 4R^2 + 4Rr + 3r^2$ and Euler's Inequality $R \geq 2r$. Indeed, $9R^2 + 8Rr + 2r^2 - 2s^2 \geq 9R^2 + 8Rr + 2r^2 - 2(4R^2 + 4Rr + 3r^2) = (R-2r)(R+2r)$.

4. Distance between circumcenter O and point T . (see Problem 2a. in Application1)

Since for $P = T$ we have $(p_a, p_b, p_c) = \left(\frac{1}{k(s-a)}, \frac{1}{k(s-b)}, \frac{1}{k(s-c)} \right)$, where $k = \sum_{cyc} \frac{1}{s-a} = \frac{4R+r}{sr}$ then $\sum_{cyc} p_b p_c a^2 = \frac{1}{k^2} \sum_{cyc} \frac{a^2}{(s-b)(s-c)} = \frac{s^2 r^2}{(4R+r)^2 sr^2} \sum_{cyc} a^2 (s-a) = \frac{s}{(4R+r)^2} \sum_{cyc} a^2 (s-a) = \frac{4s^2 r (R+r)}{(4R+r)^2}$ and, therefore,

$$OT = \sqrt{R^2 - \frac{4s^2 r (R+r)}{(4R+r)^2}}.$$

And by the way we obtain inequality $s^2 \leq \frac{R^2 (4R+r)^2}{4r((R+r))}$, which also can be

proved using Gerretsen's Inequality $s^2 \leq 4R^2 + 4Rr + 3r^2$ and Euler's Inequality $R \geq 2r$.

* Since $ab + bc + ca = s^2 + 4Rr + r^2$, $a^2 + b^2 + c^2 = 4s^2 - 2(ab + bc + ca) = 2(s^2 - 4Rr - r^2)$, $a^3 + b^3 + c^3 = 3abc + (a + b + c)^3 - 3(a + b + c)(ab + bc + ca) = 3 \cdot 4Rrs + 8s^3 - 6s(s^2 + 4Rr + r^2) = 2s(s^2 - 6Rr - 3r^2)$ we obtain

$$\sum_{cyc} a^2(s - a) = 2s(s^2 - 4Rr - r^2) - 2s(s^2 - 6Rr - 3r^2) = 4rs(R + r)$$

5. Distance between circumcenter O and point E (see Problem 2b. in Application1)

Since for $P = E$ we have $(p_a, p_b, p_c) = \frac{1}{s}(s - a, s - b, s - c)$ then $\sum_{cyc} p_b p_c a^2 = \frac{1}{s^2} \sum_{cyc} (s - b)(s - c)a^2 = \frac{1}{s^2} \sum_{cyc} (a^2 s^2 - a^2 s(b + c) + a^2 bc) = a^2 + b^2 + c^2 + \frac{abc(a + b + c)}{s^2} - \frac{(a + b + c)(ab + bc + ca)}{s} + \frac{3abc}{s} = 2(s^2 - 4Rr - r^2) + 8Rr - 2(s^2 + 4Rr + r^2) + 12Rr = 4r(R - r)$ and, therefore, $OE = \sqrt{R^2 - 4r(R - r)} = R - 2r$ and, by the way, our calculation of QE give us one more proof of Euler's Inequality.

6. Distance between circumcenter O and point L (Lemoine's point).

Since for $P = L$ we have $(p_a, p_b, p_c) = \frac{1}{a^2 + b^2 + c^2}(a^2, b^2, c^2)$ then $\sum_{cyc} p_b p_c a^2 = \frac{1}{(a^2 + b^2 + c^2)^2} \sum_{cyc} b^2 c^2 \cdot a^2 = \frac{3a^2 b^2 c^2}{(a^2 + b^2 + c^2)^2}$ and, therefore, $OL = \sqrt{R^2 - \frac{3a^2 b^2 c^2}{(a^2 + b^2 + c^2)^2}} = \sqrt{R^2 - \frac{48R^2 r^2 s^2}{(a^2 + b^2 + c^2)^2}} = R \sqrt{1 - \frac{48F^2}{(a^2 + b^2 + c^2)^2}}$ and, by the way, our calculation of QL give us one more proof of Weitzenböck's inequality $a^2 + b^2 + c^2 \geq 4\sqrt{3}F$.

Remark.

Since $(a^2 + b^2 + c^2)^2 - 48F^2 = (a^2 + b^2 + c^2)^2 - 3(2a^2 b^2 + 2b^2 c^2 + 2c^2 a^2 - a^4 - b^4 - c^4) = 4(a^4 + b^4 + c^4 - a^2 b^2 - a^2 c^2 - b^2 c^2)$ then

$$OL = 2R \sqrt{\frac{a^4 + b^4 + c^4 - a^2 b^2 - a^2 c^2 - b^2 c^2}{(a^2 + b^2 + c^2)^2}}$$

Problem 4.

Let ABC be a triangle with sidelengths a, b, c and let M be any point lying on circumcircle

of $\triangle ABC$. Find the maximum and minimum of the the following expression:

- a) $a \cdot MA^2 + b \cdot MB^2 + c \cdot MC^2$ (All Israel Math Olympiad);
- ★b) $\tan A \cdot MA^2 + \tan B \cdot MB^2 + \tan C \cdot MC^2$ if $\triangle ABC$ is acute angled triangle;

- ★c) $\sin 2A \cdot MA^2 + \sin 2B \cdot MB^2 + \sin 2C \cdot MC^2$;
- ★d) $a^2 \cdot MA^2 + b^2 \cdot MB^2 + c^2 \cdot MC^2$;
- ★e) $\frac{MA^2}{s-a} + \frac{MB^2}{s-b} + \frac{MC^2}{s-c}$.
- ★f) $(s-a)MA^2 + (s-b)MB^2 + (s-c)MC^2$

Solution.

First we consider a common approach to the all these problems represented in the following general formulation:

Let α, β, γ be real numbers such that $\alpha + \beta + \gamma \neq 0$ and let M be any point lying on circumcircle of a triangle ABC with sidelengths a, b, c and circumradius R . Find the maximal and the minimal values of the expression:

$$D(M) := \alpha \cdot MA^2 + \beta \cdot MB^2 + \gamma \cdot MC^2.$$

Let P be a point on the plane with barycentric coordinates $(p_a, p_b, p_c) = \frac{1}{\alpha + \beta + \gamma}(\alpha, \beta, \gamma)$. Then, by replacing origin O in the Leibnitz Formula with M , we obtain

$$MP^2 = \sum_{cyc} p_a MA^2 - \sum_{cyc} p_b p_c a^2 = \frac{1}{\alpha + \beta + \gamma} \sum_{cyc} \alpha \cdot MA^2 - \frac{1}{(\alpha + \beta + \gamma)^2} \sum_{cyc} \beta \gamma a^2 \iff$$

$$D(M) = (\alpha + \beta + \gamma) MP^2 + \frac{1}{\alpha + \beta + \gamma} \sum_{cyc} \beta \gamma a^2 = (\alpha + \beta + \gamma) \left(MP^2 + \sum_{cyc} p_b p_c a^2 \right).$$

Since $\sum_{cyc} p_b p_c a^2$ isn't depend from M then the problem reduces to finding the largest and smallest value of $(\alpha + \beta + \gamma) MP^2$. Wherein if $\alpha + \beta + \gamma < 0$ then $\max((\alpha + \beta + \gamma) MP^2) = (\alpha + \beta + \gamma) \min MP^2$ and $\min((\alpha + \beta + \gamma) MP^2) = (\alpha + \beta + \gamma) \max MP^2$.

Bearing in mind the application of the general case to the problems listed above, and also not to overload the text, we assume further that $\alpha + \beta + \gamma > 0$ and that point P is interior with respect to circumcircle. Hence,

Then if d is the distant between point P and circumcenter O then $\max MP = R + d$ and $\min MP = R - d$.

$$\max D(M) = (\alpha + \beta + \gamma) \left((R + d)^2 + \sum_{cyc} p_b p_c a^2 \right)$$

and

$$\min D(M) = (\alpha + \beta + \gamma) \left((R - d)^2 + \sum_{cyc} p_b p_c a^2 \right).$$

Coming back to the listed above subproblems we obtain:

a) Since $(\alpha, \beta, \gamma) = (a, b, c)$, $P = I$, $(p_a, p_b, p_c) = \left(\frac{a}{2s}, \frac{b}{2s}, \frac{c}{2c}\right)$, $d = OI = \sqrt{R^2 - 2Rr}$ and $\sum_{cyc} p_b p_c a^2 = 2Rr$ (see **Distance between circumcenter O and incenter I**) then for $D(M) = a \cdot MA^2 + b \cdot MB^2 + c \cdot MC^2$ we obtain $\max D(M) = (a + b + c) \left((R + \sqrt{R^2 - 2Rr})^2 + 2Rr \right) = 4Rs (R + \sqrt{R^2 - 2Rr})$ and $\min D(M) = (a + b + c) \left((R - \sqrt{R^2 - 2Rr})^2 + 2Rr \right) = 4Rs (R - \sqrt{R^2 - 2Rr})$.

b) Since

$$(\alpha, \beta, \gamma) = (\tan A, \tan B, \tan C), \quad (p_a, p_b, p_c) = (\cot B \cot C, \cot C \cot A, \cot A \cot B),$$

$$d = OH = \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2}, \quad \tan A + \tan B + \tan C = \frac{2sr}{s^2 - (2R + r)^2}$$

and $\sum_{cyc} p_b p_c a^2 = 2 \left(s^2 - (2R + r)^2 \right)$ (see **Distance between circumcenter O and orthocenter H**) then for

$$D(M) = \tan A \cdot MA^2 + \tan B \cdot MB^2 + \tan C \cdot MC^2$$

we we obtain

$$\max D(M) = (\tan A + \tan B + \tan C) \left(\left(R + \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2} \right)^2 + 2 \left(s^2 - (2R + r)^2 \right) \right) =$$

$$\frac{2sr}{s^2 - (2R + r)^2} \cdot 2R \left(R + \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2} \right) = \frac{4Rrs \left(R + \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2} \right)}{s^2 - (2R + r)^2}$$

and

$$\min D(M) = \frac{4Rrs \left(R - \sqrt{9R^2 + 8Rr + 2r^2 - 2s^2} \right)}{s^2 - (2R + r)^2}$$

c) Since

$$(\alpha, \beta, \gamma) = (\sin 2A, \sin 2B, \sin 2C), \quad P = O,$$

$$(p_a, p_b, p_c) = \left(\frac{\cos A}{\sin B \sin C}, \frac{\cos B}{\sin C \sin A}, \frac{\cos C}{\sin A \sin B} \right)$$

and and $d = OO = 0$ then

$$D(M) = \sin 2A \cdot MA^2 + \sin 2B \cdot MB^2 + \sin 2C \cdot MC^2 = (\sin 2A + \sin 2B + \sin 2C) \sum_{cyc} \frac{\cos B}{\sin C \sin A} \cdot \frac{\cos C}{\sin A \sin B} a^2 =$$

$$4 \sin A \sin B \sin C \sum_{cyc} \frac{a^2 \cos B \cos C}{\sin^2 A \sin C \sin B} = 4 \sum_{cyc} \frac{a^2 \cos B \cos C}{\sin A} = 8R^2 \sum_{cyc} \sin A \cos B \cos C.$$

That is for any point M that lies on circumcircle $D(M)$ is the constant, namely

$$\sum_{cyc} \sin 2A \cdot MA^2 = 8R^2 \sum_{cyc} \sin A \cos B \cos C.$$

d) Since

$$(\alpha, \beta, \gamma) = (a^2, b^2, c^2), \quad P = L, \quad (p_a, p_b, p_c) = \frac{1}{a^2 + b^2 + c^2} (a^2, b^2, c^2),$$

$$d = OL = R \sqrt{1 - \frac{48F^2}{(a^2 + b^2 + c^2)^2}}, \quad \sum_{cyc} p_b p_c a^2 = \frac{3a^2 b^2 c^2}{(a^2 + b^2 + c^2)^2} = \frac{48R^2 F^2}{(a^2 + b^2 + c^2)^2}$$

(see **Distance between circumcenter O and Lemoine point L**) then for

$$D(M) = a^2 \cdot MA^2 + b^2 \cdot MB^2 + c^2 \cdot MC^2$$

we obtain

$$\max D(M) = (a^2 + b^2 + c^2) \left(R^2 \left(1 + \sqrt{1 - \frac{48F^2}{(a^2 + b^2 + c^2)^2}} \right)^2 + \frac{48R^2 F^2}{(a^2 + b^2 + c^2)^2} \right) =$$

$$\frac{R^2}{a^2 + b^2 + c^2} \left(\left(a^2 + b^2 + c^2 + \sqrt{(a^2 + b^2 + c^2)^2 - 48F^2} \right)^2 + 48F^2 \right) =$$

$$2R^2 \left(2\sqrt{a^4 + b^4 + c^4 - a^2 b^2 - a^2 c^2 - b^2 c^2} + a^2 + b^2 + c^2 \right)$$

because $(a^2 + b^2 + c^2)^2 - 48F^2 = 4(a^4 + b^4 + c^4 - a^2 b^2 - a^2 c^2 - b^2 c^2)$ and $(t + \sqrt{t^2 - 48F^2})^2 + 48F^2 = 2t(\sqrt{t^2 - 48F^2} + t)$, where $t = a^2 + b^2 + c^2$.

Also,

$$\min D(M) = (a^2 + b^2 + c^2) \left(R^2 \left(1 - \sqrt{1 - \frac{48F^2}{(a^2 + b^2 + c^2)^2}} \right)^2 + \frac{48R^2 F^2}{(a^2 + b^2 + c^2)^2} \right) =$$

$$\frac{R^2}{a^2 + b^2 + c^2} \left(\left(a^2 + b^2 + c^2 - \sqrt{(a^2 + b^2 + c^2)^2 - 48F^2} \right)^2 + 48F^2 \right) =$$

$$2R^2 \left(a^2 + b^2 + c^2 - 2\sqrt{a^4 + b^4 + c^4 - a^2 b^2 - a^2 c^2 - b^2 c^2} \right)$$

e) Since $(\alpha, \beta, \gamma) = \left(\frac{1}{s-a}, \frac{1}{s-b}, \frac{1}{s-c} \right)$, $P = T$, $(p_a, p_b, p_c) = \left(\frac{1}{k(s-a)}, \frac{1}{k(s-b)}, \frac{1}{k(s-c)} \right)$,

where $k = \sum_{cyc} \frac{1}{s-a} = \frac{4R+r}{sr}$, $d = OT = \sqrt{R^2 - \frac{4s^2r(R+r)}{(4R+r)^2}}$ and

$\sum_{cyc} p_b p_c a^2 = \frac{4s^2r(R+r)}{(4R+r)^2}$ (see **Distance between circumcenter O and**

T) then for $D(M) = \frac{MA^2}{s-a} + \frac{MB^2}{s-b} + \frac{MC^2}{s-c}$ we obtain

$$\max D(M) = \left(\frac{1}{s-a} + \frac{1}{s-b} + \frac{1}{s-c} \right) \left(\left(R + \sqrt{R^2 - \frac{4s^2r(R+r)}{(4R+r)^2}} \right)^2 + \frac{4s^2r(R+r)}{(4R+r)^2} \right) =$$

$$\frac{4R+r}{sr} \cdot 2R \left(R + \frac{\sqrt{R^2(4R+r)^2 - 4rs^2(R+r)}}{4R+r} \right) = \frac{2R \left(R(4R+r) + \sqrt{R^2(4R+r)^2 - 4rs^2(R+r)} \right)}{sr}$$

and

$$\min D(M) = \frac{2R \left(R(4R+r) - \sqrt{R^2(4R+r)^2 - 4rs^2(R+r)} \right)}{sr}$$

f) Since $(\alpha, \beta, \gamma) = (s-a, s-b, s-c)$, $P = E$, $(p_a, p_b, p_c) = \frac{1}{s}(s-a, s-b, s-c)$,

$\sum_{cyc} p_b p_c a^2 = 4r(R-r)$, $d = OE = R - 2r$ (see **Distance between**

circumcenter O and E) then for $D(M) = (s-a)MA^2 + (s-b)MB^2 + (s-c)MC^2$ we obtain

$$\max D(M) = s \left((R+R-2r)^2 + 4r(R-r) \right) = 4sR(R-r)$$

and

$$\min D(M) = s \left((R - (R-2r))^2 + 4r(R-r) \right) = 4Rsr = abc.$$

Problem 5.

Let a, b, c be sidelengths of a triangle ABC . Find point O in the plane such that the sum

$$\frac{OA^2}{b^2} + \frac{OB^2}{c^2} + \frac{OC^2}{a^2}$$

is minimal.

Solution.

Let P be point on the plane with barycentric coordinates $(p_a, p_b, p_c) = \left(\frac{1}{kb^2}, \frac{1}{kc^2}, \frac{1}{ka^2} \right)$, where $k = \frac{1}{b^2} + \frac{1}{c^2} + \frac{1}{a^2}$.

Then by Leibnitz Formula

$$OP^2 = \sum_{cyc} p_a OA^2 - \sum_{cyc} p_b p_c a^2 = \frac{1}{k} \sum_{cyc} \frac{OA^2}{b^2} - \frac{1}{k^2} \sum_{cyc} \frac{1}{c^2 a^2} \cdot a^2 =$$

$$\frac{1}{k} \sum_{cyc} \frac{OA^2}{b^2} - \frac{1}{k^2} \sum_{cyc} \frac{1}{c^2} = \frac{1}{k} \left(\sum_{cyc} \frac{OA^2}{b^2} - 1 \right).$$

Hence, $\sum_{cyc} \frac{OA^2}{b^2} = k \cdot OP^2 + 1$ and, therefore, $\min \sum_{cyc} \frac{OA^2}{b^2} = 1 = \sum_{cyc} \frac{PA^2}{b^2}$. That is $\sum_{cyc} \frac{OA^2}{b^2}$ is minimal iff $O = P$, where P is intersect point of cevians AA_1, BB_1, CC_1 such that $\frac{BA_1}{A_1C} = \frac{F_c}{F_b} = \frac{p_c}{p_b} = \frac{c^2}{a^2}, \frac{CB_1}{B_1A} = \frac{p_a}{p_c} = \frac{a^2}{b^2}, \frac{AC_1}{C_1B} = \frac{p_b}{p_a} = \frac{b^2}{c^2}$.

Problem 6. Let ABC be a triangle with sidelengths $a = BC, b = CA, c = AB$ and let s, R and r be semiperimeter, circumradius and inradius of $\triangle ABC$, respectively.

For any point P lying on incircle of $\triangle ABC$ let

$$D(P) := aPA^2 + bPB^2 + cPC^2.$$

Prove that $D(P)$ is a constant and find its value in terms of s, R and r .

Solution.

Let I be incener of $\triangle ABC$ and let (i_a, i_b, i_c) be barycentric coordinates of I . Since $(i_a, i_b, i_c) = \frac{1}{2s}(a, b, c)$ and $PI = r$ then applying Leibnitz Formula for distance between points I and P we obtain $r^2 = PI^2 = \sum_{cyc} i_a \cdot PA^2 - \sum_{cyc} i_b i_c a^2 =$

$$\frac{1}{2s} \sum aPA^2 - \frac{1}{4s^2} \sum_{cyc} bca^2 = \frac{1}{2s} \sum_{cyc} aPA^2 - \frac{abc \cdot 2s}{4s^2} = \frac{1}{2s} \sum_{cyc} aPA^2 - \frac{4Rrs}{2s} =$$

$$\frac{1}{2s} \sum aPA^2 - 2Rr.$$

Hence, $\sum_{cyc} aPA^2 = 2s(r^2 + 2Rr)$.

Area of a triangle, equation of a line and equation of a circle in barycentric coordinates.

1. **Area of a triangle.**

First we recall that for any two vectors \mathbf{a}, \mathbf{b} on the plane is defined skew product $\mathbf{a} \wedge \mathbf{b} := \|\mathbf{a}\| \|\mathbf{b}\| \sin(\widehat{\mathbf{a}, \mathbf{b}})$ and if $(a_1, a_2), (b_1, b_2)$ are Cartesian coordinates of \mathbf{a}, \mathbf{b} , respectively, then

$$\mathbf{a} \wedge \mathbf{b} = \det \begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix} = a_1 b_2 - a_2 b_1.$$

Geometrically $\mathbf{a} \wedge \mathbf{b}$ is oriented (because $\mathbf{a} \wedge \mathbf{b} = -\mathbf{b} \wedge \mathbf{a}$) area of parallelogram defined by vectors \mathbf{a}, \mathbf{b} . Obvious that $\mathbf{a} \wedge \mathbf{b} = 0$ iff \mathbf{a}, \mathbf{b} are collinear (in particular $\mathbf{a} \wedge \mathbf{a} = 0$ for any \mathbf{a}).

Using coordinate definition of skew product easy to prove that it is bilinear, that is $(\mathbf{a} + \mathbf{b}) \wedge \mathbf{c} = \mathbf{a} \wedge \mathbf{c} + \mathbf{b} \wedge \mathbf{c}$ (then also $\mathbf{a} \wedge (\mathbf{c} + \mathbf{b}) = -(\mathbf{c} + \mathbf{b}) \wedge \mathbf{a} = -(\mathbf{c} \wedge \mathbf{a} + \mathbf{b} \wedge \mathbf{a}) = (-\mathbf{c} \wedge \mathbf{a}) + (-\mathbf{b} \wedge \mathbf{a}) = \mathbf{a} \wedge \mathbf{c} + \mathbf{a} \wedge \mathbf{b}$) and $(p\mathbf{a}) \wedge \mathbf{b} = \mathbf{a} \wedge (p\mathbf{b}) = p(\mathbf{a} \wedge \mathbf{b})$ for any real p .

For any three point K, L, M on the plane which are not collinear we will use common notation $[K, L, M]$ for oriented area of $\triangle KLM$ which equal to $\frac{1}{2} \overrightarrow{KL} \wedge \overrightarrow{KM}$ (in the case if K, L, M are collinear we obtain $[K, L, M] = 0$). Regular area of $\triangle KLM$ is $\frac{1}{2} |\overrightarrow{KL} \wedge \overrightarrow{KM}|$.

Let P, Q, R be three point on the plane and $(p_a, p_b, p_c), (q_a, q_b, q_c), (r_a, r_b, r_c)$ be, respectively their barycentric coordinates with respect to triangle ABC . Then $\overrightarrow{AP} = p_a \overrightarrow{AA} + p_b \overrightarrow{AB} + p_c \overrightarrow{AC}$ and, similarly, $\overrightarrow{AQ} = q_b \overrightarrow{AB} + q_c \overrightarrow{AC}$, $\overrightarrow{AR} = r_b \overrightarrow{AB} + r_c \overrightarrow{AC}$.

Hence, $\overrightarrow{PQ} = (q_b - p_b) \overrightarrow{AB} + (q_c - p_c) \overrightarrow{AC}$, $\overrightarrow{PR} = (r_b - p_b) \overrightarrow{AB} + (r_c - p_c) \overrightarrow{AC}$ and, therefore,

$$\begin{aligned} 2[P, Q, R] &= \overrightarrow{PQ} \wedge \overrightarrow{PR} = \left((q_b - p_b) \overrightarrow{AB} + (q_c - p_c) \overrightarrow{AC} \right) \wedge \left((r_b - p_b) \overrightarrow{AB} + (r_c - p_c) \overrightarrow{AC} \right) = \\ &= (q_b - p_b)(r_c - p_c) \overrightarrow{AB} \wedge \overrightarrow{AC} + (q_c - p_c)(r_b - p_b) \overrightarrow{AC} \wedge \overrightarrow{AB} = \\ &= ((q_b - p_b)(r_c - p_c) - (r_b - p_b)(q_c - p_c)) \overrightarrow{AB} \wedge \overrightarrow{AC} = 2[A, B, C] \cdot \det \begin{pmatrix} q_b - p_b & r_b - p_b \\ q_c - p_c & r_c - p_c \end{pmatrix}. \end{aligned}$$

Thus,

$$[P, Q, R] = \det \begin{pmatrix} q_b - p_b & r_b - p_b \\ q_c - p_c & r_c - p_c \end{pmatrix} \cdot [A, B, C].$$

Or, since

$$\det \begin{pmatrix} q_b - p_b & r_b - p_b \\ q_c - p_c & r_c - p_c \end{pmatrix} = (q_b - p_b)(r_c - p_c) - (r_b - p_b)(q_c - p_c) =$$

$$p_b q_c + p_c r_b + q_b r_c - p_c q_b - p_b r_c - q_c r_b = \det \begin{pmatrix} 1 & p_b & p_c \\ 1 & q_b & q_c \\ 1 & r_b & r_c \end{pmatrix} = \det \begin{pmatrix} p_a & p_b & p_c \\ q_a & q_b & q_c \\ r_a & r_b & r_c \end{pmatrix}$$

(because $1 - p_b - p_c = p_a, 1 - q_b - q_c = q_a, 1 - r_b - r_c = r_a$) and, therefore, we obtain more representative form of obtained correlation (Areas Formula)

$$\text{(AF)} \quad [P, Q, R] = \det \begin{pmatrix} p_a & p_b & p_c \\ q_a & q_b & q_c \\ r_a & r_b & r_c \end{pmatrix} [A, B, C].$$

Using this formula we can to do important conclusion, namely:

Points P, Q, R are collinear iff $\det \begin{pmatrix} p_a & p_b & p_c \\ q_a & q_b & q_c \\ r_a & r_b & r_c \end{pmatrix} = 0$.

From that immediately follows that set of points on the plane with barycentric coordinates (x, y, z) such that $\det \begin{pmatrix} x & y & z \\ q_a & q_b & q_c \\ r_a & r_b & r_c \end{pmatrix} = 0$ is line which passed

through points $Q(q_a, q_b, q_c)$ and $R(r_a, r_b, r_c)$, that is $\det \begin{pmatrix} x & y & z \\ q_a & q_b & q_c \\ r_a & r_b & r_c \end{pmatrix} = 0$ is equation of line in barycentric coordinates.

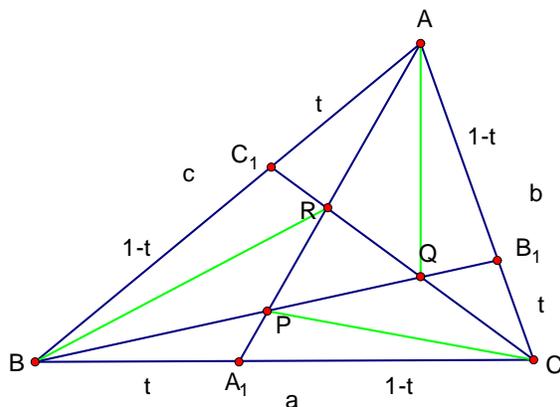
As another application of formula (AF) we will solve the following

Problem 7:

Let AA_1, BB_1, CC_1 be cevians of a triangle ABC such that $\frac{AB_1}{B_1C} = \frac{CA_1}{A_1B} = \frac{BC_1}{C_1A} = \frac{1-t}{t}$.

Find the ratio $\frac{[P, Q, R]}{[A, B, C]}$.

Solution.



Let $(p_a, p_b, p_c), (q_a, q_b, q_c), (r_a, r_b, r_c)$ be, respectively, barycentric coordinates of points P, Q, R . Then $\frac{A_1B}{A_1C} = \frac{t}{1-t} = \frac{p_c}{p_b}, \frac{B_1C}{B_1A} = \frac{t}{1-t} = \frac{p_a}{p_c}$.

Noting that $\frac{p_a}{p_c} = \frac{t}{1-t} = \frac{t^2}{t(1-t)}, \frac{p_b}{p_c} = \frac{1-t}{t} = \frac{(1-t)^2}{t(1-t)}$ we can conclude that $p_a = kt^2, p_b = k(1-t)^2, p_c = kt(1-t)$, for some k and since $p_a + p_b + p_c = 1$ we obtain $k(t^2 + (1-t)^2 + t(1-t)) = 1 \iff k(t^2 - t + 1) = 1 \iff k = \frac{1}{t^2 - t + 1}$.

Hence,

$$p_a = \frac{t^2}{t^2 - t + 1}, p_b = \frac{(1-t)^2}{t^2 - t + 1}, p_c = \frac{t(1-t)}{t^2 - t + 1}.$$

Since $\frac{q_c}{q_a} = \frac{1-t}{t}$ and $\frac{q_b}{q_a} = \frac{t}{1-t}$ we, as above, obtain

$$q_a = \frac{t(1-t)}{t^2 - t + 1} = p_c, q_b = \frac{t^2}{t^2 - t + 1} = p_a, q_c = \frac{(1-t)^2}{t^2 - t + 1} = p_b,$$

that is $(q_a, q_b, q_c) = (p_c, p_a, p_b)$ and, similarly, $(r_a, r_b, r_c) = (p_b, p_c, p_a)$.
Hence,

$$\frac{[P, Q, R]}{[A, B, C]} = \det \begin{pmatrix} p_a & p_b & p_c \\ p_c & p_a & p_b \\ p_b & p_c & p_a \end{pmatrix} =$$

$$\begin{aligned} p_a^3 + p_b^3 + p_c^3 - 3p_a p_b p_c &= (p_a + p_b + p_c)^3 - 3(p_a + p_b + p_c)(p_a p_b + p_b p_c + p_c p_a) = \\ 1 - 3(p_a p_b + p_b p_c + p_c p_a) &= \frac{1}{(t^2 - t + 1)^2} \left(t^2(1-t)^2 + (1-t)^3 t + t^3(1-t) \right) = \\ \frac{t(1-t) \left(t(1-t) + (1-t)^2 + t^2 \right)}{(t^2 - t + 1)^2} &= \frac{t(1-t)}{t^2 - t + 1}. \end{aligned}$$

Equation of a circle in barycentric coordinates.

Let O be center of a circle with radius R . And let P be any point on lying on this circle. If (o_a, o_b, o_c) and $(p_a, p_b, p_c) = (x, y, z)$ be, respectively, barycentric coordinates of O and P then

$$\text{by Leybnitz Formula } OP^2 = \sum_{cyc} p_a OA^2 - \sum_{cyc} p_b p_c a^2 \iff$$

$$\text{(EC)} \quad R^2 = xOA^2 + yOB^2 + zOC^2 - yza^2 - zxb^2 - xyc^2.$$

In particular, if O and R be circumcenter and circumradius of $\triangle ABC$ then $xOA^2 + yOB^2 + zOC^2 = R^2(x + y + z) = R^2$ and, therefore,

$$\text{(ECc)} \quad yza^2 + zxb^2 + xyc^2 = 0$$

is equation of circumcircle of $\triangle ABC$.

By replacing O and R in **(EC)** with I (incenter) and r (inradius) we obtain $r^2 = xIA^2 + yIB^2 + zIC^2 - yza^2 - zxb^2 - xyc^2$. Since $IA = \frac{b+c}{a+b+c} \cdot l_a$, where l_a is length of angle bisector from A and $l_a = \frac{2\sqrt{bcs(s-a)}}{b+c}$ then $IA^2 = \frac{(b+c)^2}{4s^2} \cdot \frac{4bcs(s-a)}{(b+c)^2} = \frac{bc(s-a)}{s}$ and, cyclic, $IB^2 = \frac{ca(s-b)}{s}$, $IC^2 = \frac{ab(s-c)}{s}$. Hence,

(E1c) $r^2 s = xbc(s - a) + yca(s - b) + zab(s - c) - yza^2 - zxb^2 - xyc^2 \iff$
 $xbc(s - a) + yca(s - b) + zab(s - c) - yza^2 - zxb^2 - xyc^2 = (s - a)(s - b)(s - c)$
 is equation of incircle.

More applications to inequalities.

For further we will use compact notations for R_a, R_b, R_c for AP, BP, CP respectively.

Application1.

For triangle $\triangle ABC$ with sides a, b, c and arbitrary interior point P holds inequalities:

$$\frac{a^2 + b^2 + c^2}{3} \leq R_a^2 + R_b^2 + R_c^2$$

Proof.

Applying Lagrange's formula to the point $G\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$ (medians intersection point) and point P , we obtain

$$PG^2 = \frac{1}{3}(PA^2 - GA^2) + \frac{1}{3}(PB^2 - GB^2) + \frac{1}{3}(PC^2 - GC^2) =$$

$$\frac{1}{3}(R_a^2 + R_b^2 + R_c^2) - \frac{1}{3} \cdot \frac{4}{9}(m_a^2 + m_b^2 + m_c^2) = \frac{1}{3}(R_a^2 + R_b^2 + R_c^2) - \frac{4}{27} \cdot \frac{3}{4}(a^2 + b^2 + c^2).$$

Hence, $PG^2 = \frac{1}{3}(R_a^2 + R_b^2 + R_c^2) - \frac{a^2 + b^2 + c^2}{9}$ and that implies inequality

$$\boxed{R_a^2 + R_b^2 + R_c^2 \geq \frac{a^2 + b^2 + c^2}{3}}$$

with equality condition $P = G$ (centroid-median intersection point).

Application2.

Let x, y, z be any real numbers such that $x + y + z = 1$ and, which can be taken as barycentric coordinates of some point P on plane, that is $(p_a, p_b, p_c) = (x, y, z)$.

Then $\sum_{cyc} xOA^2 - \sum_{cyc} yza^2 = OP^2 \geq 0$ yields inequality

$$\text{(R)} \quad \sum_{cyc} xR_a^2 \geq \sum_{cyc} yza^2,$$

where $R_a := OA, R_b := OB, R_c := OC$ and O is any point in the triangle $T(a, b, c)$.

In homogeneous form this inequality becomes

$$\text{(Rh)} \quad \sum_{cyc} x \cdot \sum_{cyc} xR_a^2 \geq \sum_{cyc} yza^2$$

which holds for any real x, y, z .

If $x := w - v, y := u - w, z := v - u$ then $\sum_{cyc} x = 0$ and we obtain $0 \geq$

$$\sum_{cyc} (u - w)(v - u) a^2 \iff$$

$$\sum_{cyc} a^2 (u - w)(u - v) \geq 0 \text{ (Schure kind Inequality).}$$

By replacing (x, y, z) in **(R)** with $\left(\frac{x}{R_a^2}, \frac{y}{R_b^2}, \frac{z}{R_c^2}\right)$ we obtain $\sum_{cyc} \frac{x}{R_a^2} \cdot \sum_{cyclic} \frac{x}{R_a^2}$.

$$R_a^2 \geq \sum_{cyc} \frac{y}{R_b^2} \cdot \frac{z}{R_c^2} a^2 \iff$$

$$\textbf{(RR)} \quad \sum_{cyc} x R_b^2 R_c^2 \cdot \sum_{cyclic} x \geq \sum_{cyc} y z a^2 R_a^2.$$

By substitution $x = aR_a, y = bR_b, z = cR_c$ in (*) we obtain $\sum_{cycl} aR_a R_b^2 R_c^2$.

$$\sum_{cyc} aR_a \geq \sum_{cyc} bR_b cR_c a^2 R_a^2 \iff \sum_{cyc} aR_b R_c \cdot \sum_{cyc} aR_a \geq abc \cdot aR_a \iff$$

$$\textbf{(H)} \quad \sum_{cyc} aR_b R_c \geq abc \text{ (T.Hayashi inequality).}$$

08.06.18 To be continued....

Footnote:

Sign \star before a problem means that this problem is proposed by author of these notes.